## Dr.Chakkrit Umpuch

## Department of Chemical Engineering

## Ubon Ratchathani University

## Example 2: Flow in Circular Pipe

(Set $\mathrm{M}=$ Momentum ( $\mathrm{kg} . \mathrm{m} / \mathrm{s}^{2}$ ), $\delta=$ Thickness of film (m), $\mathrm{V}_{\mathrm{z}}=$ Velocity $(\mathrm{m} / \mathrm{s})$ and $\mathrm{P}=$ Pressure $\left(\mathrm{N} / \mathrm{m}^{2}\right)$


Fig. 2 Flow in circular pipe in horizontal direction

Apply general law of conservation momentum (force balance)

## Term 1 <br> Term 2 <br> Term 3

$\left(\begin{array}{l}\text { Rate of momentum in } \\ \text { Shell in z-direction } \\ \text { by convection }\end{array}\right)-\left(\begin{array}{l}\text { Rate of momentum } \\ \text { out shell in } z+\Delta z \\ \text { by convection }\end{array}\right)+\left(\begin{array}{l}\text { Rate of momentum } \\ \text { in shell in r-direction } \\ \text { by molecular diffusion }\end{array}\right)$

## Term 4

## Term 5

## Term 6



For term $6=0$ (assume steady state system)

For term 1: Rate of momentum in shell at $\mathrm{z}=\mathrm{z}$ by convection

$$
\left.(\text { mass flow rate })\left(\mathrm{v}_{\mathrm{z}}\right)\right|_{\mathrm{z}=\mathrm{z}}=\left.\left(\rho \cdot \mathrm{v}_{\mathrm{z}} \cdot 2 \uparrow \mathrm{r} \cdot \Delta \mathrm{r}\right) \mathrm{v}_{\mathrm{z}}\right|_{\mathrm{z}=\mathrm{z}}
$$

For term 2: Rate of momentum out shell at $\mathrm{z}=\mathrm{z}+\Delta \mathrm{z}$ by convection (mass flow rate) $\left.\left(\mathrm{v}_{\mathrm{z}}\right)\right|_{z=\mathrm{z}+\Delta \mathrm{z}}=\left.\left(\rho \cdot \mathrm{v}_{\mathrm{z}} \cdot 2 \llbracket \mathrm{r} . \Delta \mathrm{r}\right) \mathrm{v}_{\mathrm{z}}\right|_{\mathrm{z}=\mathrm{z}+\Delta \mathrm{z}}$

For term 3: Rate of momentum in shell at $r=r$ by diffusion

$$
\left.(2 \llbracket \mathrm{r} . \Delta \mathrm{r}) \tau_{\mathrm{rz}}\right|_{\mathrm{r}=\mathrm{r}}
$$

For term 4: Rate of momentum out shell at $r=r+\Delta r$
$\left.(29 \mathrm{r} . \Delta \mathrm{r}) \tau_{\mathrm{rz}}\right|_{\mathrm{r}=\mathrm{r}+\Delta \mathrm{r}}$

For term 5: Sum of external forces acting on shell


Be careful with the sign of each term.

Because the flow is in horizontal, no gravitational force

## Combine all terms

So, from momentum balance around shell

$$
\begin{array}{r}
\left.\left(\rho . v_{z} \cdot 2 \pi r \cdot \Delta r\right) v_{z}\right|_{z}-\left.\left(\rho \cdot v_{z} \cdot 2 \pi r \cdot \Delta r\right) v_{z}\right|_{z+\Delta z}+\left.(2 \pi r \cdot \Delta z) \tau_{r z}\right|_{r} \\
-\left.(2 \pi r . \Delta z) \tau_{r z}\right|_{r+\Delta r}+\left.(2 \pi r . \Delta r) P\right|_{z}-\left.(2 \pi r \cdot \Delta r) P\right|_{z+\Delta z}=0
\end{array}
$$

Divided through by 2q $\Delta r \Delta z$
$-\left(\frac{\left.r \rho v_{z}^{2}\right|_{z+\Delta z}-\left.r \rho v_{z}^{2}\right|_{z}}{\Delta z}\right)-\left(\frac{\left.r \tau_{r z}\right|_{r+\Delta r}-\left.r \tau_{r z}\right|_{r}}{\Delta r}\right)-\left(\frac{\left.r P\right|_{z+\Delta z}-\left.r P\right|_{z}}{\Delta z}\right)=0$

Set limit $\Delta \mathbf{r} \rightarrow \mathbf{0}$, limit $\Delta \mathbf{z} \rightarrow \mathbf{0}$

$$
\begin{aligned}
& -\lim _{\Delta z \rightarrow 0}\left(\frac{\left.r \rho v_{z}^{2}\right|_{z+\Delta z}-r \rho v_{z}^{2} \|_{z}}{\Delta z}\right)-\lim _{\Delta r \rightarrow 0}\left(\frac{\left.r \tau_{r z}\right|_{r+\Delta r}-\left.r \tau_{r z}\right|_{r}}{\Delta r}\right)-\lim _{\Delta z \rightarrow 0}\left(\frac{\left.r P\right|_{z+\Delta z}-\left.r P\right|_{z}}{\Delta z}\right) \\
& =0 \\
& -\frac{d\left(\rho r v_{z}^{2}\right)}{d z}-\frac{d\left(r \tau_{r z}\right)}{d r}-\frac{d(r P)}{d z}=0
\end{aligned}
$$

## For incompressible fluid ( $\rho=$ constant)

$-\frac{\rho d\left(r v_{z}^{2}\right)}{d z}-\frac{d\left(r \tau_{r z}\right)}{d r}-\frac{d(r P)}{d z}=0$

Since $\mathbf{V}_{\mathbf{z}} \neq \mathrm{f}(\mathrm{z}), \frac{d v_{z}}{d z}=\mathbf{0}$ and $\frac{d\left(v_{z}^{z}\right)}{d z}=0$.
$-\frac{d\left(r . \tau_{r z}\right)}{d r}-\frac{d(r . P)}{d z}=0$

Simplified equation by approximation $d P \approx \Delta P$ and $d z \approx \Delta z \approx L$ and $r \neq f$ (z):
$r \frac{d P}{d z} \approx r \frac{\Delta P}{\Delta z}=\frac{r\left(P_{L}-P_{0}\right)}{L}$

Then we obtain $1^{\text {st }}$ ODE w.r.t. $\tau_{r z}$;
$-\frac{d\left(r . \tau_{r z}\right)}{d r}-\frac{r\left(P_{L}-P_{0}\right)}{L}=0$

Apply Newton's Law: $\quad \boldsymbol{\tau}_{r z}=-\frac{\mu d v_{z}}{d r}$
$-\frac{d}{d r}\left(r \cdot\left(-\mu \frac{d v_{z}}{d r}\right)\right)-\frac{r\left(P_{L}-P_{0}\right)}{L}=0$

For isothermal system, $\mu=$ constant
$\mu \frac{d}{d r}\left(r \frac{d v_{z}}{d r}\right)+\frac{r\left(P_{0}-P_{L}\right)}{L}=0$
$\frac{d}{d r}\left(r \frac{d v_{z}}{d r}\right)=-\frac{r\left(P_{0}-P_{L}\right)}{\mu L}$

Perform the equation by indefinite integration ( ${ }^{\text {st }}$ )
$\int d\left(r \frac{d v_{z}}{d r}\right)=\int-\frac{r\left(P_{0}-P_{L}\right)}{\mu L} d r$

$$
\begin{aligned}
& r \frac{d v_{z}}{d r}=-\frac{r^{2}\left(P_{0}-P_{L}\right)}{2 \mu L}+C_{1} \\
& \frac{d v_{z}}{d r}=-\frac{r\left(P_{0}-P_{L}\right)}{2 \mu L}+\frac{C_{1}}{r}
\end{aligned}
$$

Perform the equation by indefinite integration ( $2^{\text {nd }}$ )

$$
\begin{aligned}
& \int d\left(v_{z}\right)=\int \frac{-r\left(P_{0}-P_{L}\right)}{2 \mu L} d r+\int \frac{C_{1}}{r} d r \\
& v_{z}=\frac{-r^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}+C_{1} \ln (r)+C_{2}
\end{aligned}
$$

Apply BC1: At $\mathrm{r}=0, \mathrm{~V}_{\mathrm{z}}=\mathrm{V}_{\mathrm{z}, \text { max }}$ (finite)
$\left(v_{z, \text { max }}\right)=-\frac{(0)^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}+C_{1}(-\infty)+C_{2}$
(finite)




Note: The above equation is $-\infty$ by means of mathematic, but in fact the equation must be finite because $\mathrm{Vz}, \max$ is finite. So, we force $\mathrm{C}_{1}=0$ in order to valid the equation.

$$
v_{z}=\frac{-r^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}+C_{1} \ln (r)+C_{z}
$$

$$
\text { Finite }=\quad \text { finite } \quad+\quad \underline{0} \quad+\mathrm{C}_{2}
$$

Substitute $\mathbf{C}_{1}$ into the equation
$v_{z}=\frac{-r^{2}\left(P_{0}-P_{\Sigma}\right)}{4 \mu L}+C_{2}$

Apply BC2: At $\mathbf{r}=\mathrm{R}, \mathrm{V}_{\mathrm{z}}=\mathbf{0}$
$0=\frac{-R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}+C_{2}$
$C_{2}=\frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}$
Substitute $\mathrm{C}_{\mathbf{2}}$ into the equation
$\nu_{z}=\frac{-r^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}+\frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}$
$v_{z}=\frac{\left(P_{0}-P_{L}\right)}{4 \mu L}\left(R^{2}-r^{2}\right)$

So we get $1^{\text {st }}$ solution as the velocity profile:
$v_{z}=\frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}\left[1-\left(\frac{r}{R}\right)^{2}\right]$

What is expression of the maximum velocity?
Since $B C 2$ at $r=0, V z=V z, m a x$, we get,
$v_{z, \max }=\frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}\left[1-\left(\frac{0}{R}\right)^{2}\right]$
$v_{z, \max }=\frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}$

What is equation of volumetric flow rate $(\mathrm{Q})$ ?
$\int_{0}^{Q} d Q=\int_{0}^{R}\left(v_{z} \cdot 2 \pi r \cdot d r\right)$
$Q=\int_{0}^{R} \frac{R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}\left[1-\left(\frac{r}{R}\right)^{2}\right] .2 \pi r . d r$
$Q=\left.\frac{2 \pi R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}\left[\frac{r^{2}}{2}-\frac{r^{4}}{4 R^{2}}\right]\right|_{0} ^{R}$
$Q=\frac{2 \pi R^{2}\left(P_{0}-P_{L}\right)}{4 \mu L}\left[\frac{4 R^{4}-2 R^{4}}{8 R^{2}}\right]$
$Q=\frac{\pi R^{4}\left(P_{0}-P_{L}\right)}{8 \mu L} ; \quad\left(Q \propto R^{4}\right)$
"The Hagen-Porseuille equation"
Hydraulic Eng. (1839, German) Physician (1841, France)

What is mean velocity $\left(\overline{v_{z}}\right)$ ?
$\bar{v}_{z}=\frac{1}{2} v_{z, \max }$
$\bar{v}_{z}=\frac{R^{2}\left(P_{0}-P_{L}\right)}{8 \mu L}$

What is Force acting on surface of pipe?
$\vec{F}=\left(\left.\tau_{r z}\right|_{r=R}\right)(2 \pi R L)$
$\vec{F}=\left(-\mu .-\frac{d v_{z}}{d \gamma^{*}}\right)(2 \pi R L)$
$\vec{F}=\mu \cdot \frac{R\left(P_{0}-P_{\mathrm{L}}\right)}{2 \mu L}(2 \pi R L)$
$\vec{F}=\pi R^{2}\left(P_{0}-P_{L}\right)$

Assumptions of the Hagen-Poiseuille Equation

1. Isothermal system
2. Laminar flow
3. Incompressible fluid ( $\mathrm{v}, \rho$ constant)
4. Newtonian fluid
5. Steady state system
6. End effects are neglected


Inverted Monometer


$$
\begin{gathered}
P_{\text {high }}=P_{1} \\
P_{\text {low }}=P_{2} \\
P_{1}=\rho_{w} g h+\rho_{w} g a+P_{x} \\
P_{2}=\rho_{\mathrm{a}} g h+\rho_{w} g a+P_{y} \\
P_{1}-P_{2}=\rho_{w} g h+\rho_{w} g a+P_{x}-\rho_{\mathrm{a}} g h-\rho_{w} g a-P_{y} \\
\text { Because } x=y, P_{x}=P_{y} \\
P_{1}-P_{2}=\left(\rho_{w}-\rho_{a}\right) g h
\end{gathered}
$$

