



เรียน รองคณบดีฝ่ายวิจัยและบริการวิชาการ ผ่านหัวหน้าภาควิชาวิศวกรรมไฟฟ้าและอิเล็กทรอนิกส์

ดังนั้น เพื่อให้การนำเสนอผลงานวิจัยเป็นไปด้วยความเรียบร้อย จึงใคร่ขออนุมัติทุนสนับสนุนเพื่อนำเสนอผลงานวิจัยดังกล่าว เป็นจำนวนเงิน 91,980.- บาท (-เก้าหมื่นหนึ่งพันเก้าร้อยแปดสิบบาทถ้วน-) ซึ่งมีรายละเอียดดังต่อไปนี้

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เรียน รองคณบดีฝ่ายวิจัยและบริการวิชาการ
เพื่อโปรดพิจารณา

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(ผู้ช่วยศาสตราจารย์ ดร.วรการ วงศ์สายเชื้อ)
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ডায়েরী নং-১৩৮/১৫

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I don't know / I don't know / I don't know
I don't know / I don't know / I don't know
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JLH
19 Nov. 58

สรุปรายละเอียดค่าใช้จ่าย

ประชุมวิชาการระดับนานาชาติ "International Conference on Environment and Renewable Energy(ICERE 2015) "

เรื่อง " Electric Bus Transit Shortest Path and Least Energy Consumption Path Based on Traffic conditions"

ระหว่างวันที่ 20-21 พฤษภาคม 2558 ณ ประเทศออสเตรเลีย

หมวดรายจ่าย	รายการ	คณะ	ม.อุบลฯ	หมายเหตุ
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ICERE 2015

International Conference on Environment and Renewable
Energy.

20-21 May 2015, Vienna, Austria

Assist. Prof Bongkoj Sookanata

Department of Electrical and Electronics Engineering, Ubon Rachatani University, Ubon Rachatani, THAILAND
INVITATION

Dear Assist. Prof Bongkoj Sookanata

We are pleased to invite you to the 2015 International Conference on Environment and Renewable Energy which will be held 20-21 May in at the Grand Hotel Wien . We confirm that the full paper of Assist. Prof Bongkoj Sookanata " Electric Bus Transit Shortest Path and Least Energy Consumption Path Based on Traffic Conditions ' has been reviewed and accepted for Oral Presentation at the conference and publication in the Proceedings. We ask Austrian consulate to issue visa to Assist. Prof . Bongkoj Sookanata for the period of the conference. For updates about program, residence, visa and other necessary information, please visit our website. In case of any questions please contact +43 660 5498409 or email adeo.office@gmail.com

Sincerely,

Elena Ringo

Technical Organizing Committee,
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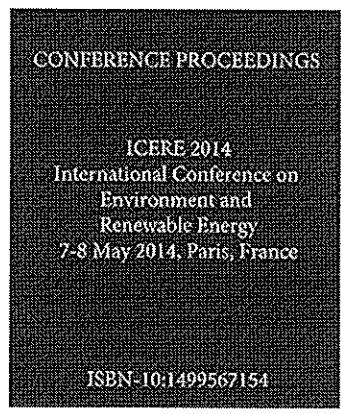
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Electric Bus Transit Shortest Path and Least Energy Consumption Path Based on Traffic Conditions

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Abstract: Long vehicle driving distance increases pollution emissions for both internal combustion engine (ICE) and electric vehicles (EVs). ICE vehicle burns fossil fuels while driving but EV uses electricity based on marginal electric power sources with high green house gas (GHG) emissions. Shortest path driving distance is very importance to minimize battery energy depletion and find the most economical route for EV. In this paper, the shortest path for multiple destinations was determined for normal traffic condition. Additionally, the path with least energy consumption was determined for electric bus-transit when some subtrips have different traffic conditions. As the results, order of visited points on least energy consumption for electric bus-transit route alters to shortest path. Amount of energy difference was presented for both shortest path and least energy consumption.

Keywords: Electric vehicle, electric bus, shortest path, least energy consumption, traffic, estimation.

1. Introduction

The distance driven by electric vehicle (EV) in all electric range depends on size of battery and power consumption by EV. In grid support EV, the electricity can be controlled based on types of fuels used. EV charging at peak load is discouraged due to high green house gas (GHG) emissions and high operating cost. Mix of power generation sources, fossil fuels-based and renewable energy sources can be controlled to reduce GHG emissions. In EV operation, electric motor consumes different power and energy at each driving speed to propel wheels. For a driving cycle, speed variation data are obtained by recording the vehicle in start, stop and speed up modes several times. Well-known standard driving cycles for driving in highway road and urban road are HWFET and UDDS driving cycles. Average speed and maximum speed on these driving cycles are different [1, 2]. Shortest path has been researched to find the minimum path distance between points for ICE vehicles. ICE vehicles need to fill their fuel tanks at nearest filling stations that usually located several kilometres apart alongside the road. Electrical vehicle has different charging method from ICE vehicle. Electricity can be supplied through household electric outlets connected to electrical grid or standalone power supply without grid connection for slow and fast charging electricity. The current that used for charging can be low current of 5-60 A for slow charging and high current more than 300 A for fast charging. Slow charging at 120-240 V can be set up at places with parking spaces such as shopping malls, apartments, or hotels but fast charging needs special equipment so it can be located in some places with safety protection. If charging units are widely available then driver may charge his car any time. At current state, the adoption of EV and charger are limited and infrastructure is not completed ready available. EV needs to find nearest charging unit in nearest distance or shortest path. Electric bus-transit is one of low operation cost transportation per person [3-5] and it is driven pass several stops as circular or loop driving. In this paper, the shortest path and the least energy consumption path of a TEV is studied. Subtrips with and without traffic jam are considered. The results show energy difference for both shortest path and least energy consumption path.

2. Shortest Path Problem and Algorithm

2.1 Shortest Path Problem

Electric bus -Transit is driven as loop passing multiple destinations or points. Paths between different any two points are called subtrips. Vehicles were driven at different speeds depending on traffic conditions. In Fig 1., point-A, B,D, E, F

are presented. Subtrips are A-B, B-C, B-E, C-D, C-F, D-E, D-F, E-F, F-A. One point that can be connected to other points and it has various subtrips.

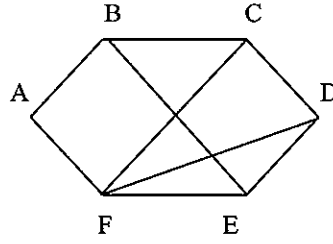


Fig.1 Multiple points and subtrips

Total distance from starting point to ending point (S_{se}) is the summation of subtrips (S_{ij}). It can be written as equation (1).

$$S_{se} = \sum_{i,j=1}^{n-1} S_{ij} \quad (1)$$

Where i and j are point numbers to be visited.

For various speeds driving, the average speed between point- i and point- j for path passing point k can be written as equation (2).

$$V_{ij} = S_{ik} + S_{jk} / \left(\frac{S_{ik}}{V_{ik}} + \frac{S_{jk}}{V_{jk}} \right) \quad (2)$$

Where S_{ik} is distance between point- i and point- k in kilometres.

V_{ik} is velocity between point- i and point- k in km/hr.

Time spent between point i and j can be calculated using equation (3)

$$t_{ij} = \frac{S_{ij}}{V_{ij}} \quad (3)$$

Where t_{ij} is traveling time from point i to point j in hour

Energy consumption between point i and j can be calculated using equation (4)

$$E_{ij} = S_{ij} \times ER \quad (4)$$

Where E_{ij} is energy consumption between point i and j in kWh

ER is rate of energy consumption in kWh/km

Shortest path problem involves finding the minimum distance of every subtrips traveled between a pair of points. The total travel distance must less than the possible distance supplied by the battery in one time charging. However EV drives on shortest path may not energy efficiency as the speed has impact on vehicle performance. For standard driving cycles such as the highway fuel economy test cycle (HWFET) and the dynamometer driving schedule (UDDS), the vehicle usage are including speed and time is repeatedly tested under road conditions and traffics on highway and urban. In UDDS, the average speed is lower than that on HWFET but energy consumption rate of EV is higher for the maximum speed of 90 and 96.4 km/h. The increasing energy consumption causes by the force variation due to acceleration and braking action on the drive tests. The energy – efficient should be considered for better energy utilization. In this paper, the number of

destinations is known but the order to visit need to be specified for the shortest path and least energy consumption on traffic condition consideration.

2.2 Shortest Path Algorithm

To find the shortest path, an algorithm was implemented using Ant Colony Optimization (ACO). The Ant colony optimization is a nature inspired meta-heuristic optimization technique which mimics the behaviour of the ants working in their colony [6].

Ant Colony Optimization (ACO) application to least energy consumption was developed as the following steps,

- Step 1: Load data including distance and speed, energy consumption rate during normal and busy hour, busy hour of a day
- Step 2: Set parameters including number of points to be visited, maximum iteration of ACO calculation, number of ants or population, alpha and beta (using 2 and 6 respectively in this paper)
- Step 3: Initialize visiting routes randomly, note that the number of routes equals number of ants
- Step 4: Initialize pheromone for each visiting point to 0.1
- Step 5: For shortest path, calculate visibility of the ant

$$\eta_{ij} = \frac{1}{D_{ij}} \quad (5)$$

For least energy consumption, calculate traveling time between points, check traffic condition and select energy consumption rate, then calculate visibility of the ant

$$\eta_{ij} = \frac{1}{E_{ij}} \quad (6)$$

where η_{ij} is visibility

D_{ij} is distance between point i and j

E_{ij} is energy consumption, note that during busy hour the consumption rate is 1.3 times increased

- Step 6: Calculate probability of each visiting point to be visited by the ant

$$P_{ij} = \frac{(\tau_{ij}^{\alpha})(\eta_{ij}^{\beta})}{\sum (\tau_{ij}^{\alpha})(\eta_{ij}^{\beta})}$$

Where τ_{ij} is pheromone of route between point i and j , η_{ij} is visibility of the ant at point i to point j

- Step 7: Select next point to be visited by chance of the route selection using probability calculated in step 6
- Step 8: Update pheromone for each visiting point after it's been visited
- Step 9: Calculate the energy consumption for each route and keep the least one in memory to compare with the least consumption obtained in the next iteration
- Step 10: Select point to create route using step 5 to 9 until the maximum iteration is met.

3. Simulation Results

The algorithm was simulated for a route of 10-point destinations. The average velocities of electric bus during busy/normal traffic conditions are also given in the Fig.2.

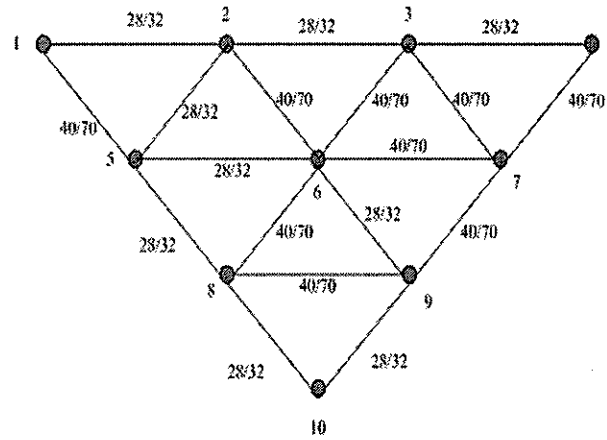


Fig 2. The studied Short Problem

Distances between points of a map shown in Fig. 2 are given in Table I.

Table I . Each Subtrip distance

Path	Distance (km)	Path	Distance (km)	Path	Distance (km)
1-2	1	3-6	6.3	6-8	8.2
2-3	1.1	3-7	9.5	6-9	3.5
3-4	2.3	4-7	10.4	7-9	9.3
1-5	6.3	5-6	3.8	8-9	8.2
2-5	4.4	6-7	6.3	8-10	3.3
2-6	7	5-8	3.8	9-10	1.8

3.1 Shortest path

In this case, the traffic condition is not considered. Using Ant Colony Optimization, the shortest path has been determined and shown in Fig 3. Distance of the path is 38.9 km. The orders of visiting points are provided in Table 2. It is assumed that the path is loop and therefore, the end point must be the same as the beginning point.

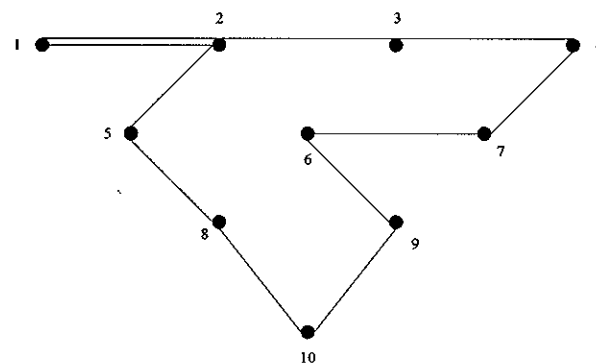


Fig 3.Shortest path without traffic considaration

Table II. The orders of visiting points for shortest path

path	orders	path	order
1	9-10-8-5-2-1-3-4-7-6-9	6	1-3-4-7-6-9-10-8-5-2-1
2	10-8-5-2-1-3-4-7-6-9-10	7	3-4-7-6-9-10-8-5-2-1-3

3	8-5-2-1-3-4-7-6-9-10-8	8	4-7-6-9-10-8-5-2-1-3-4
4	5-2-1-3-4-7-6-9-10-8-5	9	7-6-9-10-8-5-2-1-3-4-7
5	2-1-3-4-7-6-9-10-8-5-2	10	6-9-10-8-5-2-1-3-4-7-6

From the results shown in table II, every point can be a beginning point. In order to travel with shortest path, the visitor follows the path shown in Fig 2, in clockwise direction or another way round. Without consideration of traffic condition, the shortest path is also least energy consumption path under assumption that the path has unique average energy consumption rate.

3.2 The least energy consumption path with traffic condition consideration

With consideration of traffic condition, the ACO is used to determine the least energy consumption path for the trip started at 8.00 am. It is assumed that the busy hours occur during 8.00 to 8.30 am. During normal traffic condition, the average velocity is 70 km/hr for the 6.3 km and greater subtrips and 32 km/hr for the rest of subtrips. During busy hours, the average velocity is 40 km/hr for the 6.3 km and greater subtrips and 28 km/hr for the rest of subtrips. The energy consumption rate for normal and busy conditions are 160.25 and 208.33 Wh/km respectively.

In this paper, it is assumed that the traffic condition is unchanged for each subtrip. It is found that the path and orders of points is arranged as 9-10-8-5-2-1-3-4-7-6-9 for the energy consumption of 6.9213 kWh and 38.9 km. For the same path with different beginning point such as 7-6-9-10-8-5-2-1-3-4-7 can cause higher energy consumption as 6.9501 kWh

Data on driving speed and traffic condition information is needed to estimate the energy demand of a vehicle especially EVs. Driving speed can be recorded by GPS or electronic devices about traffic conditions are difficult to get. Possible traffic conditions can be predicts from experience the traffic jam such as front of schools and workplaces on week day. The higher energy consumption of EV is expected when traffic jam occurs and average speed decreases. Shortest path may changes depending on conditions of the road. It is importance for development EV infrastructure in the future especially for electric bus-transit.

4. Conclusion

A shortest path problem was determined using Ant Colony Optimization algorithm. The solution of a shortest path problem is presented with order of points to visit. Traffic jams on some subtrips have impacts on overall energy consumption when the average speed of electric bus decreases compared to that at normal traffic condition. Least energy consumption can have minimum distance but has different order of visit points from shortest path. Both shortest path and least energy consumption should be considered for energy-efficient electric vehicles.

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